INSTRUMENTED INDENTATION FOR DETERMINATION OF FULL RANGE STRESS-STRAIN CURVES

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Abstract: One common method for the determination of full range stress-strain curves by instrumented indentation is presented and validated for an aluminium alloy. This method relates properties describing the indentation force-depth curve with those describing the uniaxial stress-strain curve as traditionally obtained from a tensile test. The first aim of this paper is to explain the basic concepts of instrumented indentation. Next, the analysis method is presented and validated. This study ends with discussing the uniqueness of the obtained solution. It is concluded that accurate determination of stress-strain behaviour can be realized, but for certain materials two indentations are needed.

Keywords: instrumented indentation, indenter, stress-strain, mystical materials

1 INTRODUCTION

Imagine one wants to obtain the local stress-strain properties of a metal in a non-destructive manner and with no restriction on specimen size and shape. This is made possible using an instrumented indentation test (IIT). In this paper the stress-strain curve of an aluminium alloy 6061-T6511 will be reconstructed by IIT [1, 2]. This alloy is widely used in commercial construction applications.

IIT is a hardness test during which execution the force on the indenter and the displacement of the indenter are recorded. After specific data analysis, this results in a force-depth curve (Figure 1). This curve is characterised by a number of parameters that are discussed in section 2. The stress-strain curve of a metal is typically characterised by its Young's modulus, strain hardening exponent and yield strength. This will be elaborated in section 3. Several methods have been proposed to relate the parameters of an indentation force-depth curve with those of a stress-strain curve. Some brief remarks are given in section 4. The curve fitting method used in this paper is fairly generic and widely used for the reconstruction of stress-strain curves. This is the topic of section 5. In section 6 the uniqueness of the obtained solution is discussed.





2 INDENTATION FORCE-DEPTH CURVE

The evolution of an indentation force-depth curve depends on the indenter type used but generally follows a characteristic pattern. This pattern is explained by means of an example, shown in Figure 2, obtained for the aluminium alloy 6061-T6511 using a Berkovich type indenter [2]. Such an indenter has the same projected area as a Vickers indenter (or a cone with a half tip angle of 70.3°) but is characterized by three facets instead of four.



Figure 2: Indentation force-depth curve for an aluminium alloy 6061T6511 obtained using a Berkovich type indenter

The loading phase of the indentation response is described by Kick's law:

$$P = C \cdot h^2 \tag{1}$$

For this specimen Kick's constant C is 27.6 GPa. The (un)loading rate and maximum load are user defined and for the sample considered, these parameters are 4.4 N/min and 3 N respectively. At the moment of maximum load, the maximum imprint depth h_{max} equals 10.19 µm.

Afterwards the material is unloaded, the indenter removed and the imprint recovers elastically. The unloading phase can be approximated by Eq. (2) in which B, m and h_r are curve fitting parameters [3].

$$P = B \cdot (h - h_r)^m \tag{2}$$

The unloading stiffness S is defined as the slope of the unloading curve near the maximum indentation depth. It can be calculated by differentiating Eq. (2) and evaluating at h_{max} :

$$S = \frac{dP}{dh}\Big|_{h_{max}} = B \cdot m \cdot (h_{max} - h_r)^{m-1} = 4491 \text{ kN/m}$$
(3)

Much of the information obtained by one single instrumented indentation test is described by the four parameters introduced above: h_r , h_{max} , C and S. For some IIT methods the work performed during loading W_T (area underneath the indentation force-depth curve during the loading phase) and unloading W_E (area underneath the indentation force-depth curve during the unloading phase) are required rather than h_r and h_{max} . For sharp indenter types, W_T and W_E contain the same information as h_r and h_{max} and are less sensitive to scatter because they are calculated based on all measured data points rather than a single value.

3 STRESS-STRAIN CURVE

The linear-elastic region of a stress-strain curve is characterized by the Young's modulus *E*. Further, the Poisson coefficient v is introduced to describe lateral restraint effects during elastic (un)loading.

In instrumented indentation of metals, the stress-strain curve in the plastic area (i.e. stress exceeds the yield strength σ_{Y}) is typically approximated by a Hollomon type equation [4]:

$$\sigma = R \cdot \epsilon^{n_H} \quad for \quad \sigma \ge \sigma_Y \tag{4}$$

With *R* the strength coefficient and n_H the strain hardening exponent. The stress in the plastic area can be rewritten by Eq. (5) when elastic strain is given by ε_{y} , and the plastic component of strain by ε_{p} .

$$\sigma = R \cdot \left(\epsilon_y + \epsilon_p\right)^{n_H} = \sigma_y \left(1 + \frac{\epsilon_p}{\epsilon_y}\right)^{n_H} = \sigma_y \left(1 + \frac{E \cdot \epsilon_p}{\sigma_y}\right)^{n_H}$$
(5)

This stress-strain model is described by (E, σ_y, n_H) or (E, σ_r, n_H) with σ_r the 'representative' stress corresponding to a particular 'representative' strain as explained in section 5.

Figure 3 plots the true stress-strain curve of the aluminium alloy investigated in this paper determined by traditional tensile testing [2]. Its model parameters are E = 66.8 GPa, $n_H = 0.8$ and $\sigma_Y = 278$ MPa.



Figure 3: Stress-strain curve of the aluminium alloy 6061-T6511

4 RELATIONSHIP BETWEEN INDENTATION FORCE-DEPTH AND STRESS-STRAIN CURVES

A point-to-point systematic relationship between an indentation force-depth curve and a stress-strain curve would lead to a non-destructive method to determine the stress-strain properties of a steel. Such relationship has only been developed for spherical indentation (Brinell type indenter) [5-7], thereby making use of numerous profound assumptions and approximations. For sharp indentation (Vickers, Berkovich or Rockwell type indenters), however, finding an immediate link between both curves is highly challenging due to the geometrical similarity of this type of indentation [8]. This means that an IIT at large depth is essentially a magnified picture of an IIT at a small depth. As a consequence, methods based on a sharp indentation are confined to providing links between the model parameters of an indentation force-depth curve and a stress-strain curve rather than between their distinct data points.

The material in the vicinity of the indentation does not remain perfectly flat, which increases the complexity of characterising the deformation and developing adequate definitions for the representative stress and strain. Two different indentation responses may occur; pile-up and sink-in as illustrated on Figure 4.



Figure 4: Pile-up (Left) and sink-in (right) influences the accuracy of stress and strain calculations

Multiple authors [5-7, 9] developed equations to predict pile-up and sink-in for certain material groups. The tendency towards pile-up increases with decreasing strain hardening exponent n_H and σ_y/E ratio [10]. Due to the many approximations which need to be made, a point-to-point relationship is limited in accuracy.

5 INSTRUMENTED INDENTATION ANALYSIS BY MEANS OF CURVE FITTING

In curve fitting methods, the indentation parameters are written as functions of the unknown stress-strain properties. This enables the reconstruction of an indentation force-depth model curve out of the stress-strain model curve and vice versa. A selected curve fitting method for sharp indentation is applied to the indentation force-depth curve of Figure 2. This specific method is valid for common engineering materials: *E* from 10 to 210 GPA, $\sigma_{\rm Y}$ from 30 to 3000 MPa and $n_{\rm H}$ from 0 to 0.5, with Poisson's ratio fixed at 0.3.

The influence of elastic deformations of both the indented metal and the indenter is captured by the reduced Young's modulus E^{\dagger} defined as:

$$E^* = \left(\frac{1-\nu^2}{E} + \frac{1-\nu_i^2}{E_i}\right)^{-1}$$
(6)

with v_i the Poisson coefficient of the indenter and E_i its Young's modulus. For a diamond indenter these values equal 0.07 and 1140 GPa respectively. The Young's modulus *E* of the aluminium alloy is 66.8 GPa and thus is the reduced Young's modulus E^{\dagger} equal to 70.4 GPa.

Next, three different universal dimensionless functions [11] are used to link both curves. Each author has its own functions but in general they have the same structure, given by the equations below [12-16].

$$\prod_{1} \left(\frac{E^{*}}{\sigma_{r}}, n \right) = \frac{C}{\sigma_{r}}$$
(7)

$$\prod_{2} \left(\frac{\mathrm{E}^{*}}{\sigma_{\mathrm{r}}}, \mathrm{n} \right) = \frac{1}{\mathrm{E}^{*}\mathrm{h}_{\mathrm{m}}} \mathrm{S}$$
⁽⁸⁾

$$\prod_{3} \left(\frac{\mathbf{E}^{*}}{\sigma_{\mathbf{r}}}, \mathbf{n} \right) = \frac{\mathbf{h}_{\mathbf{r}}}{\mathbf{h}_{\mathbf{m}}} \tag{9}$$

These functions are expressed as a function of the representative stress σ_r corresponding with a plastic strain of 0.033, rather than the yield strength σ_y . The choice of representative strain simplifies the solution to Eqs. (7)-(9), since with this value \prod_1 was empirically observed to be independent of n_H (Figure 5). σ_r is further also denoted as $\sigma_{0.033}$. By solving Eqs. (7), (8) and (9) the unknown material properties can be obtained. To illustrate this principle the functions will be solved graphically.

Given that the Young's modulus is known for aluminium alloys, only the Hollomon model parameters $(n_H and \sigma_y)$ of the stress-strain curve remain unknown. Thus only two dimensionless functions are needed to solve the problem. Because Le et al. [13] proved that Eq. (8) and Eq.(9) are dependent for sharp indentation, Eq. (7), Figure 5 and Eq. (8), Figure 6 are used to solve the problem.



With C and \vec{E} a priori known (27.6 GPa and 70.4 GPa respectively) a straight line with slope equal to C/\vec{E} can be drawn on Figure 5. From the intersection of this line with the function \prod_1 , the representative stress $\sigma_{0.033}$ is determined as 337.4 MPa. S and h_{max} are 4500 kN/m and 10.19 µm respectively and thus from

Figure 6 it follows that $n_H = 0.088$. The yield stress can be calculated using Eq. (5), resulting in $\sigma_y = 278$ MPa.

Figure 7 shows the resulting stress-strain curve which is in good approximation with the one obtained from the tensile test (10% error on n_H and 2% error on σ_Y).



Figure 7: IIT has the potential to provide good approximations for stress-strain behaviour

6 UNIQUENESS OF THE SOLUTION

If the Young's modulus is not known in advance, it is impossible to reconstruct the stress-strain curve uniquely by sharp indentation, given the dependence of Eqs. (8) and (9). It is clear from Figure 8 that different materials may yield the same indentation force-depth curve for sharp indentation, independent of the dimensionless relations used. Such materials are referred to as 'mystical materials'. By using a second and different indenter (e.g. a 60° cone, see Figure 8) in a so called 'dual indenter method', different materials are uniquely distinguishable. Several dual indenter methods exist [2, 13, 17-20] but with other dimensionless functions than Eqs. (7)-(9). Apart from adopting a second indenter, increasing the penetration depth decreases the likeliness that the force-depth curve is the same for the different materials. However, with increasing penetration depth, unpredictable and therefore undesired frictional effects become increasingly pronounced.



Figure 8: Impossibility to uniquely reconstruct the stress-strain curve with only one Berkovich indenter [2]

7 CONCLUSION

Instrumented indentation allows for the construction of uniaxial stress-strain curves using the recorded indentation force-depth curve as an input. This paper has illustrated a common method, based on curve fitting and applied for sharp indenters. A case study indicates that satisfactory results can be obtained. Transforming an indentation force-depth curve into a uniaxial stress-strain curve is challenging due to poorly quantifiable phenomena such as pile-up and sink-in, and the existence of mystical materials. It is shown that for uniquely determining the stress-strain properties two indentations with different indenters may be necessary. Both indentations can then be analysed using the single indentation method explained in this paper. This leads to a sufficient number of independent equations to solve for the stress-strain curve parameters.

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